

Publicații:

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S. Nedevschi, R. Danescu, D. Frentiu, T. Marita, F. Oniga, C. Pocol, R. Schmidt, T. Graf, "[High Accuracy Stereo Vision System for Far Distance Obstacle Detection](#)," in *Proc. IEEE Intelligent Vehicles Symposium (IV'04)*, Parma, Italy, 14-17 June 2004, pp. 292-297, ISBN 0-7803-8311-7

S. Nedevschi, R. Danescu, D. Frentiu, T. Marita, F. Oniga, C. Pocol, "Extraction of Dynamic Traffic Description Using Multiple Stereovision Equipped Vehicles," in *Proc. Computing, Communications and Control*

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Capitole de carte (2):

S. Nedevschi, R. Danescu, T. Marita, F. Oniga, C. Pocol, S. Bota, M.-M. Meinecke, M. A. Obojski, "Stereovision-Based Sensor for Intersection Assistance", chapter in "[Advanced Microsystems for Automotive Applications 2009: Smart Systems for Safety, Sustainability and Comfort](#)", editors G. Meyer, J. Valldorf, W. Gessner, published by Springer, pp.129-164, ISBN 978-3-642-00744-6

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